

2013 - 2014

Spring

Midt 2 / Solutions

- 1) a) (5 pts.) Let A be an $n \times n$ matrix. Prove that $\det(\text{adj}A) = (\det A)^{n-1}$ where $\text{adj}A$ is the adjoint matrix of A .

$$A^{-1} = \frac{1}{\det A} \cdot \text{adj}A \Rightarrow \text{adj}A = (\det A) \cdot A^{-1}$$

$$\begin{aligned} \det(\text{adj}A) &= \det(\det A \cdot A^{-1}) \\ &= (\det A)^n (\det A)^{-1} \\ &= (\det A)^{n-1} \end{aligned}$$

- b) (4 pts. each) The product of two 3×3 matrices A and B is known to be

$$AB = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} \text{ and the adjoint matrix } \text{adj}A \text{ has determinant 4.}$$

Find the determinants

- $\det(A^{-1})$.
- $\det(A)$.
- $\det(B)$.
- $\det(A^2B^3)$.

Show your work.

i) $\det(\text{adj}A) = (\det A)^2 = 4 \Rightarrow \det A = \pm 2 \Rightarrow \det A^{-1} = \pm \frac{1}{2}$

ii) $\det A = \pm 2$

iii) $\det(AB) = 24$ & $\det A = \pm 2 \Rightarrow \det B = \pm 12$

iv) $\det(A^2B^3) = (\det A)^2 (\det B)^3 = \pm 4 \cdot (\pm 12)^3$.

- 2) (25 pts.) Let $S = \{v_1, v_2, v_3, v_4, v_5\}$ be a subset of \mathbb{R}^3 containing 5 vectors. Let $A = [v_1 v_2 v_3 v_4 v_5]$ be the 3×5 matrix obtained by writing the vectors in the set S as its columns. Suppose that by applying elementary row operations one may reduce the

matrix A to an echelon matrix $E = \begin{bmatrix} 1 & 0 & 2 & 3 & 4 \\ 0 & 3 & 3 & 1 & 5 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$.

Let W be the subspace of \mathbb{R}^3 spanned by the set S .

- a) Find a basis for W consisting entirely of vectors from the set S .

$$E = \begin{bmatrix} 1 & 0 & 2 & 3 & 4 \\ 0 & 3 & 3 & 1 & 5 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix} \xrightarrow{\frac{1}{6}R_3} \begin{bmatrix} 1 & 0 & 2 & 3 & 4 \\ 0 & 3 & 3 & 1 & 5 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{matrix} -4R_3 + R_1 \\ -5R_3 + R_2 \\ -\frac{1}{3}R_2 \end{matrix}} \begin{bmatrix} 1 & 0 & 2 & 3 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = R$$

e.i. ind.

v_1, v_2 & v_5 are lin. independent, since they are lead 1's in R .

$\therefore B_W = \{v_1, v_2, v_5\}$

- b) Is there a vector in \mathbb{R}^3 that is not in W ? Explain your answer.

No! Because $\dim W = 3 = \dim \mathbb{R}^3 \Rightarrow W = \mathbb{R}^3$.

- c) Are the vectors v_1, v_2, v_3 linearly independent? If not, express one of them as a linear combination of the others.

No, they are not lin. indep.

$$v_3 = 2v_1 + v_2$$

3) (10 pts. each)

- a) Let A be a 2×5 matrix such that the linear system $AX = b$ is consistent for all 2×1 column vectors b . What is the nullity of A ? **Explain your result.**

Since the linear system $AX = b$ is consistent for all 2×1 column vector b , every 2×1 column vector belongs to the column space of A so that the dimension of the column space is 2. Thus, $\text{rank}(A) = 2$.
 $\text{rank}(A) + \text{null}(A) = 5 \Rightarrow \text{null}(A) = 3$.

- b) Let A be a 4×5 matrix whose nullity is 1. Are the rows of A linearly independent? **Explain your answer.**

$$\text{rank}(A) + \frac{\text{null}(A)}{1} = 5 \Rightarrow \text{rank}(A) = 4$$

$\text{rank}(A) = \#$ linearly independent rows of A
and it is equal to the number of rows of A
Thus, the rows of A are linearly independent.

- c) Let A be a 3×5 matrix whose columns span \mathbb{R}^3 . What is the nullity of A ?

As the columns of A span \mathbb{R}^3 , the dimension of the column space is 3 i.e. $\text{rank}(A) = 3$
 $\text{rank}(A) + \text{null}(A) = 5 \Rightarrow \text{null}(A) = 2$.

- 4) Let $\{v_1, v_2, \dots, v_k\}$ be the basis for the proper subspace W (i.e. $W \neq \{0_v\}$ and $W \neq V$) of the vector space V , and suppose that the vector v of V is not in W . Prove that v_1, v_2, \dots, v_k, v are linearly independent. **Show your work.**

$v \notin W$

Suppose that v_1, v_2, \dots, v_k, v are lin. dependent.

Then there are constants $c_1, c_2, \dots, c_k, c \in \mathbb{R}$, not all zero s.t.

$$c_1 v_1 + c_2 v_2 + \dots + c_k v_k + c v = 0.$$

If $c = 0$, then $c_1 v_1 + c_2 v_2 + \dots + c_k v_k = 0$ for some constants c_1, \dots, c_k not all zero but it's a contradiction since $\{v_1, \dots, v_k\}$ is a basis for W .

$$\text{Then } c \neq 0 \Rightarrow v = \left(-\frac{c_1}{c}\right)v_1 + \dots + \left(-\frac{c_k}{c}\right)v_k$$

i.e. $v \in \text{span}\{v_1, \dots, v_k\} = W$

This is also a contradiction.

$\therefore v_1, v_2, \dots, v_k, v$ are lin. independent.

Exercise 29 in 4.4