BILKENT UNIVERSITY Department of Mathematics

MATH 225, LINEAR ALGEBRA and DIFFERENTIAL EQUATIONS, Solution of Homework set¹ # 15

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Homework problems from the 2nd Edition, SECTION 4.5

5)

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Row basis: The three row vectors of **E**. Column basis: The first, second, and fourth column vectors of **A**.

12) Reduced row echelon form of the matrix is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

Row basis: The first three row vectors of E. Column basis: The first, second, and fifth column vectors of A.

14) Consider the matrix **A** having the given vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4$ as its column vectors. The reduced row echelon form **E** of **A** is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & 1/5 & 2 \\ 0 & 1 & 2/5 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Therefore the vectors \vec{v}_1 and \vec{v}_2 are L.I.

16) Similar to the previous problem, the reduced row echelon form of A is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

Therefore, $\vec{v}_1, \vec{v}_2, \vec{v}_4$ and \vec{v}_5 are L.I.

¹I made every effort to avoid the calculation errors and/or typos while I prepared the solution set. You are responsible to check all the solutions and correct the errors if there is any. If you find any errors and/or misprints, please notify me.

17) Let the matrix $\mathbf{A} = [\vec{v}_1 \ \dots \ \vec{v}_k \ \vec{e}_1 \ \dots \ \vec{e}_n]$. Then its reduced row echelon form \mathbf{E} is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & -3 & 0 & 2 \\ 0 & 1 & 2 & 0 & -1 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix}.$$

Therefore, \vec{v}_1, \vec{v}_2 and \vec{e}_2 are the basis vectors.

20) Similar to the previous problem consider the matrix **A**, the its reduced row echelon form of **A** is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & 0 & -5/2 & 0 & 2 \\ 0 & 1 & 0 & 3/2 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

So, $\vec{v}_1, \vec{v}_2, \vec{e}_1$ and \vec{e}_2 are the basis vectors.

23) Consider the transpose of the coefficient matrix A. The reduced row echelon form E of A^T is

$$\mathbf{E} = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

So, the fourth equation is redundant, we have actually three equations.

29) The rank of the $m \times n$ matrix **A** is at most m < n, and therefore is less than the number n of its column vectors. Hence the column vectors $\vec{a}_1, \vec{a}_2, ... \vec{a}_n$, of **A** are linearly dependent, so there exists a linear combination

$$y_1 \vec{a}_1 + y_2 \vec{a}_2 + \dots + y_n \vec{a}_n = \vec{0}, \qquad \mathbf{A} \vec{y} = \vec{0}$$

with not all the coefficients being zero. If

$$\vec{x} = [x_1, x_2, \dots x_n]^T$$

is one solution of the equation $\mathbf{A}\vec{x} = \vec{b}$ then

$$\mathbf{A}(\vec{x} + \vec{y}) = \mathbf{A}\vec{x} + \mathbf{A}\vec{y} = \vec{b} + \vec{0} = \vec{b},$$

so $\vec{x} + \vec{y}$ is a second different solution. Thus solutions of the equation are not unique.

34) If no row interchanges are involved, then (for any k) the space spanned by the first k row vectors of **A** is never changed in the process of reducing **A** to the echelon matrix **E**; this follows immediately from the proof of Theorem 2 in this section. Hence the first r row vectors of **A** span the r-dimensional space Row(**A**), and therefore are linearly independent.