Bäcklund transformations for discrete Painlevé equations\textsuperscript{1} : Discrete P\textsubscript{II} - P\textsubscript{V}

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Abstract

Transformation properties of discrete Painlevé equations are investigated by using an algorithmic method. This method yields explicit transformations which relates the solutions of discrete Painlevé equations, discrete P\textsubscript{II}-P\textsubscript{V}, with different values of parameters. The particular solutions which are expressible in terms of the discrete analogue of the classical special functions of discrete Painlevé equations can also be obtained from these transformations.

1 Introduction

Painlevé and his school classified the integrable second order equation of the form $y'' = f(x, y, y')$ where $f$ is rational in $y$ and $y'$ and analytic in $x$, whose solutions have no movable critical points, and discovered six transcendental equations that are called Painlevé equations, P\textsubscript{I} - P\textsubscript{VI} \cite{1, 2, 3}. Their general solutions can not be expressed in terms of the known elementary functions and can be regarded as nonlinear analogues of the classical special functions. However, P\textsubscript{II} - P\textsubscript{VI} have rational solutions and solutions expressible in terms of the classical special functions for certain values of parameters. P\textsubscript{II} - P\textsubscript{VI} also possess Bäcklund transformations which relate solutions of the same equation with different values of parameters, or to solution of another equation of Painlevé type \cite{4, 5, 6}. Although, Painlevé equations were first discovered from strictly mathematical considerations, they have appeared in physical applications. For example, P\textsubscript{III} arises in the Ising model \cite{7}, and P\textsubscript{IV} appears in quantum gravity \cite{8}.

Discrete analogues of the Painlevé equations are nonautonomous mappings that are integrable in the same sense as the continues Painlevé equations \cite{9, 10, 11}, and

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recently have attracted much attention. The discrete Painlevé equations, dP\textsubscript{I}-dP\textsubscript{VI}, which have the form

\[ x_{n+1} = \frac{f_1(x_n; n) + x_{n-1}f_2(x_n; n)}{f_3(x_n; n) + x_{n-1}f_4(x_n; n)} \]  

\text{(1.1)}

where \(f_j(x_n; n)\) are polynomials of degree at most four in \(x_n\) [12]. In continuous limit, the discrete Painlevé equations yield a Painlevé equation, though some of the discrete Painlevé equations have limits more then one Painlevé equation. Moreover, discrete Painlevé equations possess properties similar to the ones of the continuous Painlevé equations. For example, discrete Painlevé equations also form coalescence cascades [9, 13, 14, 15], possess Lax’s pairs [16, 17, 18], have rational solutions for certain values of parameters [19, 20, 21], have particular solutions for certain parameter values expressible in terms of the discrete analogue of the special functions [16, 19, 22, 23, 24], and have Bäcklund transformations [19, 22, 24]. Discrete Painlevé equations also appear in physics, for example, the computation of a certain partition function in a model of two-dimensional quantum gravity led discrete P\textsubscript{I} [25]. The only difference between continuous and discrete Painlevé equations is that the continuous Painlevé equations have unique canonical form up to a Möbius transformation, but there is more then one inequivalent discrete equation which has the Painlevé equation as its continuous limit.

Recently, Sakai [26] characterized the Painlevé equations in the framework of the theory of rational surfaces, and showed that the translation part of the affine Weyl groups give rise to discrete Painlevé equations whereas the whole group acts as their groups of symmetries, Bäcklund transformations. The six continues Painlevé equations appear as degenerate cases of this construction. The geometrical description in the framework of the affine Weyl group \(E^{(1)}_6\) of the asymmetric q-P\textsubscript{V} and asymmetric d-P\textsubscript{IV} which are known as discrete analogues of the Painleve VI equation, was given in the recent work of Grammaticos, Ramani and Ohta [27].

In this article, we investigate the transformation properties of the discrete Painlevé equations by using an algorithmic method which is similar to the method developed by Fokas and Ablowitz [5] for investigating the transformation properties of the continuous equations of the Painlevé type. In [5], for given continuous Painlevé equations

\[ v'' = P_2 (v')^2 + P_1 v' + P_3 \]  

\text{(1.2)}

where \(P_1, P_2, P_3\) depend on \(v\), independent variable \(z\) and set of parameters \(\alpha\), the transformation of type

\[ u(z; \hat{\alpha}) = \frac{v' + av^2 + bv + c}{dv^2 + ev + f} \]  

\text{(1.3)}

where \(a, b, ..., d\) depend on \(z\) only and \(u(z; \hat{\alpha})\) solves some second order equation of the Painlevé type with set of parameters \(\hat{\alpha}\), was considered. If we solve (1.3) for \(v'\),
we obtain

\[ v' = (du - a)v^2 + (eu - b)v + (fu - c). \tag{1.4} \]

That is, solution \( v \) of the given equation of Painlevé type also satisfies a Riccati equation with the coefficients depending linearly on the solution \( u \) of related Painlevé type equation. By following the similar argument, for a given discrete Painlevé equation (1.1) with parameter set \( \alpha \), we consider discrete Riccati equation, that is

\[ x_{n+1} = \frac{A_n x_n + B_n}{C_n x_n + D_n} \tag{1.5} \]

where \( A_n = A_{1,n} y_n + A_{0,n}, \quad B_n = B_{1,n} y_n + B_{0,n}, \quad C_n = C_{1,n} y_n + C_{0,n}, \) and \( D_n = D_{1,n} y_n + D_{0,n} \) such that \( y_n \) solves discrete equation of Painlevé type with parameter set \( \hat{\alpha} \). The aim is to determine \( A_{j,n}, \ldots, D_{j,n}, j = 0, 1 \) requiring that (1.5) defines a one-to-one invertible map between the solutions \( x_n \) of a given discrete Painlevé equation, and solutions \( y_n \) of some second order discrete equation of Painlevé type. This method yields explicit transformations between a given discrete Painlevé equation and the same discrete Painlevé equation but with different values of its parameters, and between two different discrete equations of Painlevé type. As an application of the method, we obtain particular solutions of discrete Painlevé equations in terms of discrete analogue of the classical special functions.

The method can be summarized as follows: From equation (1.5), one writes

\[ x_{n-1} = -\frac{D_{n-1} x_n - B_{n-1}}{C_{n-1} x_n - A_{n-1}}. \tag{1.6} \]

Substituting \( x_{n+1} \) and \( x_{n-1} \) given in (1.5) and (1.6) respectively into given discrete Painlevé equation (1.1) gives an equation which is polynomial for \( x_n \) with the coefficients depending on \( A_{j,n}, \ldots, D_{j,n}, \quad j = 0, 1, \) \( y_n \) and \( y_{n-1} \). Now, we choose \( A_{j,n}, \ldots, D_{j,n} \) such that the polynomial for \( x_n \) reduces to a polynomial of degree one or of degree two. That is,

\[ E(y_n, y_{n-1} ; n)x_n + F(y_n, y_{n-1} ; n) = 0, \tag{1.7} \]

or

\[ E(y_n, y_{n-1} ; n)x_n^2 + F(y_n, y_{n-1} ; n)x_n + G(y_n, y_{n-1} ; n) = 0. \tag{1.8} \]

If one solves (1.7) or (1.8) for \( x_n \) and substitutes into (1.5), (1.5) yields a discrete equation of Painlevé type for \( y_n \). It turns out that, similar to the case of continuous Painlevé equations, discrete \( P_\Pi - P_V \) admit transformations of both types (1.7) and (1.8). However, discrete \( P_{VI} \) does not admit a transformation of type (1.7). In this article we will consider the transformation of type (1.7), the type (1.8) will be considered later and published elsewhere.
2 Discrete Painlevé II Equation

In this section, we consider d-P\(_{\text{II}}\) equation:

\[
x_{n+1} + x_{n-1} = \frac{z_n x_n + a}{1 - x_n^2},
\]

(2.1)

where \(z_n = \alpha n + \beta\), and \(\alpha, \beta, a\) are constants. Substituting \(x_{n+1}\) and \(x_{n-1}\) given in (1.5) and (1.6) respectively into (2.1) gives the following polynomial for \(x_n\),

\[
(z_n x_n + a)(C_n x_n + D_n)(C_{n-1} x_n - A_{n-1}) = (1 - x_n^2)\left[(A_n x_n + B_n)(C_{n-1} x_n - A_{n-1}) - (C_n x_n + D_n)(D_{n-1} x_n - B_{n-1})\right]
\]

(2.2)

Our goal now is to choose \(A_n, ..., D_n\) in such a way that (2.2) becomes a linear equation for \(x_n\). (2.2) reduces to a linear equation for \(x_n\),

\[
(B_n + B_{n-1} + z_n - 2)x_n = B_n - B_{n-1} - a
\]

(2.3)

with the choice of \(A_n = C_n = D_n = 1\). Without loss of generality, we may choose \(B_n = y_n - \frac{1}{2} z_n - \frac{1}{4} \alpha + 1\). Hence, equations (1.5) and (2.3) respectively give

\[
y_n = (x_n + 1)(x_{n+1} - 1) + \frac{1}{2} z_n + \frac{1}{4} \alpha
\]

(2.4)

and

\[
x_n = \frac{y_n - y_{n-1} + \nu}{y_n + y_{n-1}}
\]

(2.5)

where \(\nu = -\frac{1}{2} \alpha - a\). Eliminating \(x_n\) between (2.4) and (2.5) leads to a discrete form of P\(_{\text{XXXIV}}\) [22]:

\[
(y_n + y_{n-1})(y_n + y_{n+1}) = \frac{\nu^2 - 4 y_n^2}{y_n - \frac{1}{2} z_n - \frac{1}{4} \alpha}.
\]

(2.6)

Miura transformation (2.5) was also given in [22].

2.1 Bäcklund Transformation for d-P\(_{\text{II}}\)

Since, (2.6) is quadratic in \(\nu\), thus \(y_n(\nu) = y_n(-\nu)\). But then, from equation (2.5)

\[
\bar{x}_n(-\nu) = \frac{y_n(-\nu) - y_{n-1}(-\nu) - \nu}{y_n(-\nu) + y_{n-1}(-\nu)}
\]

\[
= \frac{y_n(\nu) - y_{n-1}(\nu) - \nu}{y_n(\nu) + y_{n-1}(\nu)}
\]

\[
= \frac{2\nu}{y_n(\nu) + y_{n-1}(\nu)}
\]

(2.7)
Hence, expressing $y_n$ in terms of $x_n$ and using $\nu = -\frac{1}{2}\alpha - a$ give the following Bäcklund transformation for d-P$_{II}$

$$\bar{x}_n = x_n - \frac{2\nu(x_n + 1)}{2(x_{n+1} - 1)(x_n + 1) - z_n x_n - a}; \quad \bar{a} = -a - \alpha. \quad (2.8)$$

Bäcklund Transformation for d-P$_{II}$ was also given in [22, 24, 28].

### 2.2 Special Solution

The transformation (2.5) breaks down if

$$y_n + y_{n-1} = 0 \quad (2.9)$$

and

$$y_n - y_{n-1} + \nu = 0. \quad (2.10)$$

By solving (2.9) and (2.10), we find that $y_n = \nu = 0$. Substituting $y_n = \nu = 0$ into (2.4) yields the following discrete Riccati equation:

$$x_{n+1} = \frac{2x_n - z_n + a + 2}{2(x_n + 1)}. \quad (2.11)$$

Therefore, particular solution of d-P$_{II}$ is characterized by (2.11), iff $a = -\frac{1}{2}\alpha$. (2.11) can be linearized by a Cole-Hopf transformation $x_n = \frac{w_n}{w_{n-1}} - 1$, and we thus obtain the discrete analogue of the Airy equation:

$$2w_{n+1} + (z_n - a)w_{n-1} - 4w_n = 0. \quad (2.12)$$

Special solution in terms of discrete Airy functions of d-P$_{II}$ was also given in [22, 23, 24].

### 3 Discrete Painlevé III Equation

In this section, we consider the following discrete Painlevé III equation, q-P$_{III}$ [14]:

$$x_{n+1}x_{n-1} = \frac{ab(x_n - c\lambda^n)(x_n - d\lambda^n)}{(x_n - a)(x_n - b)}, \quad (3.1)$$

where $a$, $b$, $c$, $d$ are constants. Using the method introduced in the introduction, we find

$$\frac{(A_n x_n + B_n)(D_n x_{n-1} - B_{n-1})}{(C_n x_n + D_n)(C_{n-1} x_n - A_{n-1})} = -\frac{ab(x_n - c\lambda^n)(x_n - d\lambda^n)}{(x_n - a)(x_n - b)}. \quad (3.2)$$
With the choice of \( D_n = -aC_n \) and \( A_n = bC_n \), equation (3.2) can be reduced to the following linear equation for \( x_n \):

\[
\left[ bC_nB_{n-1} + aC_{n-1}B_n + ab(c + d)\lambda^{2n}C_{n-1} \right] x_n = abcd\lambda^{2n}C_{n-1} - B_nB_{n-1}. \tag{3.3}
\]

Without loss of generality we may let, \( B_n = \mu\lambda^{n+\frac{1}{2}}y_n \), \( C_n = 1 \), where \( \mu^{2} = abcd \). Then equations (1.5) and (3.3) become

\[
y_n = \frac{x_{n+1}(x_n - a) - bx_n}{\mu\lambda^{n+\frac{1}{2}}} \tag{3.4}
\]

and

\[
x_n = \frac{\mu^{2}\lambda^{n+\frac{1}{2}}(1 - y_ny_{n-1})}{a\mu\lambda y_n + b\mu y_{n-1} + ab\lambda^{\frac{1}{2}}(c + d)} \tag{3.5}
\]

respectively. Eliminating \( x_n \) between the equations (3.4) and (3.5) leads to the following discrete equation for \( y_n \)

\[
(y_ny_{n+1} - 1)(y_ny_{n-1} - 1) = - \frac{\tilde{\lambda}^{n}(y_n - \alpha)(y_n - \frac{1}{\alpha})(y_n - \beta)(y_n - \frac{1}{\beta})}{(\gamma y_n - \lambda^{n})}, \tag{3.6}
\]

where

\[
\alpha = - \frac{\mu}{ac\lambda^{\frac{1}{2}}}, \quad \beta = - \frac{\mu}{ad\lambda^{\frac{1}{2}}}, \quad \gamma = - \frac{\mu\lambda^{\frac{1}{2}}}{ab}, \quad \tilde{\lambda} = \lambda^{-1}. \tag{3.7}
\]

Equation (3.6) is the special case, \( \delta = 0 \), of q-P\( V \) [14]:

\[
(y_ny_{n+1} - 1)(y_ny_{n-1} - 1) = \frac{\tilde{\lambda}^{2n}(y_n - \alpha)(y_n - \frac{1}{\alpha})(y_n - \beta)(y_n - \frac{1}{\beta})}{(\gamma y_n - \lambda^{n})(\delta y_n - \lambda^{n})}. \tag{3.8}
\]

Thus there exists the one to one correspondence given by (3.4) and (3.5) between the solutions of q-P\( III \) and (3.6).

### 3.1 Bäcklund Transformation for discrete P\( III \)

Bäcklund transformation can be obtained by finding two sets of \( \{\alpha, \beta, \gamma\} \) such that (3.6) is invariant. It should be noted that equation (3.6) is invariant under the change of parameters

\[
\tilde{\alpha} = \frac{1}{\alpha}, \quad \tilde{\beta} = \frac{1}{\beta}, \quad \tilde{\gamma} = \gamma. \tag{3.9}
\]

By using (3.9) and following the same procedure given in section 2.1, we obtain the following Bäcklund transformation for q-P\( III \)

\[
\tilde{x}_n = \frac{\tilde{d}\lambda x_n[a x_{n+1}(x_n - a) + bx_{n-1}(x_n - b) - 2abx_n + ab(c + d)\lambda^{n}]}{c[b x_{n+1}(x_n - a) + a\lambda^{2}x_{n-1}(x_n - b) - (a^{2}\lambda^{2} + b^{2})x_n + ab(c + d)\lambda^{n+1}]};
\]

\[
\tilde{a} = \frac{bd}{\lambda c}, \quad \tilde{b} = \frac{a\lambda d}{c}, \quad \tilde{c} = \frac{dc}{c}.
\]
3.2 Special Solution

The transformation (3.5) breaks down if

\[ y_n y_{n-1} - 1 = 0, \]  

(3.11)

and

\[ a \mu \lambda y_n + b \mu y_{n-1} + ab \lambda^2 (c + d) = 0. \]  

(3.12)

By solving equations (3.11) and (3.12), we find that

\[ y_n = - \frac{bc}{\mu \sqrt{\lambda}}, \] and \[ \lambda \mu^2 = b^2 c^2. \]

Then, (3.4) leads to the following discrete Riccati equation

\[ x_{n+1} = \frac{b(x_n - c \lambda^n)}{x_n - a}. \]  

(3.13)

Therefore, particular solution of \( q - \text{P}_\text{III} \) is characterized by (3.13), iff \( \lambda a d = b c \). (2.11) can be linearized by a Cole-Hopf transformation \( x_n = a + \frac{w_n}{w_{n-1}} \), and we thus obtain the discrete analogue of the Bessel equation [16]:

\[ w_{n+1} - b(a - c \lambda^n)w_{n-1} + (a - b)w_n = 0. \]  

(3.14)

The linearisability condition for \( q - \text{P}_\text{III} \) and the particular solution expressible in terms of the discrete analogue of the Bessel functions were also obtained in [15, 16, 29]

4 Discrete Painlevé IV Equation

In this section, we consider the discrete Painlevé IV equation, \( d - \text{P}_\text{IV} \):

\[ (x_{n+1} + x_n)(x_{n-1} + x_n) = \frac{(x_n^2 - a^2)(x_n^2 - b^2)}{(x_n - z_n^2 - c^2)}, \]  

(4.1)

where \( z_n = \alpha n + \beta \), and \( a, b, \alpha, \beta \) are constants. Equation (4.1) gives the following equation after substituting \( x_{n+1} \) and \( x_{n-1} \) respectively given in (1.5) and (1.6),

\[ \frac{[C_n x_n^2 + (D_n + A_n)x_n + B_n][C_{n-1} x_n^2 - (D_{n-1} + A_{n-1})x_n + B_{n-1}]}{(C_n x_n + D_n)(C_{n-1} x_n - A_{n-1})} = \frac{(x_n^2 - a^2)(x_n^2 - b^2)}{(x_n - z_n^2 - c^2)}. \]  

(4.2)
(4.2) can be reduced to a linear equation for \( x_n \)
\[
x_n = \frac{-(y_{n-1} - z_n + \mu + \alpha)(y_n - z_n - \mu - \alpha) + z_n^2 - c^2}{y_n + y_{n-1}},
\]
(4.3) 
with the choice of \( A_n = -(y_n - z_n + \mu) \), \( B_n = ab \), \( C_n = 1 \), and \( D_n = y_n - z_n - \mu - \alpha \), where \( \mu = -\frac{1}{2}(a + b + \alpha) \). With these choices, the equation (1.5) yields
\[
x_{n+1} = \frac{-(y_n - z_n + \mu)x_n + ab}{x_n + y_n - z_n - \mu - \alpha}.
\]
(4.4) 
By eliminating \( x_n \) between (4.3) and (4.4), we obtain d-P\(^{\text{IV}}\)
\[
(y_{n+1} + y_n)(y_{n-1} + y_n) = \frac{(y_n^2 - a^2)(y_n^2 - b^2)}{(y_n - z_n)^2 - c^2},
\]
(4.5) 
where
\[
z_n = z_n + \frac{1}{2}\alpha, \quad a^2 = [c - \frac{1}{2}(a + b - \alpha)]^2, \quad b^2 = [c + \frac{1}{2}(a + b - \alpha)]^2, \quad c^2 = \frac{1}{4}(a - b)^2.
\]
(4.6) 
If we replace \( y_n \) with \( \bar{x}_n \) in (4.4), we thus obtain the following Bäcklund transformation for d-P\(^{\text{IV}}\)
\[
\bar{x}_n = -\frac{x_{n+1}(x_n - z_n - \mu - \alpha) - x_n(z_n - \mu - ab)}{(x_{n+1} + x_n)},
\]
(4.7) 
such that \( \bar{x}_n \) solves d-P\(^{\text{IV}}\) with the parameters \( \bar{a}, \bar{b}, \bar{c} \) given by (4.6). The Bäcklund transformation (4.7) for discrete Painlevé IV equation was first given in [19].

### 4.1 Special Solution

The transformation (4.3) breaks down if
\[
y_n + y_{n-1} = 0,
\]
(4.8) 
and
\[
-(y_{n-1} - z + \mu + \alpha)(y_n - z_n - \mu - \alpha) + z_n^2 - c^2 = 0.
\]
(4.9) 
\( y_n = \mu + \alpha + c = 0 \) solve the equations (4.8) and (4.9). Equation (4.4) yields the following discrete Riccati equation,
\[
x_{n+1} = \frac{(a + b - c + z_n)x_n + ab}{x_n + c - z_n}.
\]
(4.10) 
after substituting \( y_n = \mu + \alpha + c = 0 \) [15, 19, 29]. Therefore, particular solution of d-P\(^{\text{IV}}\) satisfies (4.10), iff \( a + b - 2c = \alpha \). Cole-Hopf transformation \( x_n = z_n - c + (w_n/w_{n-1}) \) transforms the Riccati equation (4.10) into the following linear equation for \( w_n \):
\[
w_{n+1} - (z_n - c + a)(z_n - c + b)w_{n-1} - 2cw_n = 0.
\]
(4.11) 
Equation (4.11) has been shown to be solvable in terms of the discrete analogues of Hermite functions [19].
5 Discrete Painlevé V Equation

In this section, we consider the q-P\(_V\) equation

\[
(x_n x_{n+1} - 1)(x_n x_{n-1} - 1) = \frac{\lambda^{2n}(x_n - a)(x_n - b)(x_n - \frac{1}{a})(x_n - \frac{1}{b})}{(cx_n - \lambda^n)(dx_n - \lambda^n)},
\]

(5.1)

where \(a, b, c, d\) are constants. Applying the method introduced in the introduction, we find

\[
[A_n x_n^2 + (B_n - C_n)x_n - D_n][-D_{n-1}x_n^2 + (B_{n-1} - C_{n-1})x_n + A_{n-1}] = \frac{\lambda^{2n}(x_n - a)(x_n - b)(x_n - \frac{1}{a})(x_n - \frac{1}{b})}{(cx_n - \lambda^n)(dx_n - \lambda^n)}. \]

(5.2)

Equation (5.2) can be reduced to a linear equation for \(x_n\) with the choice of

\[
A_n = \mu \lambda^n, \quad B_n = y_n - (a + b)\mu \lambda^n, \quad C_n = y_n, \quad D_n = -abA_n, \quad \text{where} \quad \mu^2 = \frac{\lambda}{abcd}.
\]

Then the equations (5.2) and (1.5) yield

\[
x_n = \frac{\mu \lambda^{n-1}(ab\lambda y_{n-1} + y_n) - (\frac{1}{c} + \frac{1}{d})\lambda^n}{y_n y_{n-1} - 1}
\]

(5.3)

and

\[
x_{n+1} = \frac{\mu \lambda^n(x_n - a - b) + y_n}{y_n x_n - ab\mu \lambda^n}.
\]

(5.4)

respectively. We obtain the following q-P\(_V\) for \(y_n\) by eliminating \(x_n\) between the equations (5.3) and (5.4):

\[
(y_n y_{n+1} - 1)(y_n y_{n-1} - 1) = \frac{\lambda^{2n}(y_n - \alpha)(y_n - \frac{1}{\alpha})(y_n - \beta)(y_n - \frac{1}{\beta})}{(\gamma y_n - \lambda^n)(\delta y_n - \lambda^n)},
\]

(5.5)

where \(\gamma = \frac{1}{a\mu}, \delta = \frac{1}{b\mu}, \alpha = \frac{\mu c}{\lambda}, \text{ and } \beta = \frac{\mu d}{\lambda} \). Therefore, we have the following Bäcklund transformation for q-P\(_V\)

\[
\bar{x}_n = \frac{\mu \lambda^n[abx_{n+1} + x_n - a - b]}{x_n x_{n+1} - 1};
\]

\[
\bar{a} = \frac{\mu c}{\lambda}, \quad \bar{b} = \frac{\mu d}{\lambda}, \quad \bar{c} = \frac{1}{a\mu}, \quad \bar{d} = \frac{1}{b\mu}.
\]

(5.6)

5.1 Special Solution

The transformation (5.3) breaks down if

\[
y_n y_{n-1} - 1 = 0,
\]

(5.7)
and
\[ \mu \lambda^{n-1} (ab \lambda y_{n-1} + y_n) - \left( \frac{1}{c} + \frac{1}{d} \right) \lambda^n = 0. \] (5.8)

If we substitute the solutions \( y_n = \frac{\lambda}{\mu c} \), and \( \lambda^2 = \mu^2 c^2 \) of (5.7) and (5.8) into (5.4), we obtain the following discrete Riccati equation [29],
\[ x_{n+1} = \frac{\lambda^n (x_n - a - b) + abd}{ab(dx_n - \lambda^n)}. \] (5.9)

Therefore, particular solution of q-P\( \text{V} \) is characterized by (5.9), iff \( c = \lambda abd \). Eq. (2.11) can be linearized by a Cole-Hopf transformation \( x_n = \frac{\lambda^n}{d} \left( 1 - \frac{w_n}{w_{n-1}} \right) \), and we thus obtain the following linear equation for \( w_n \)
\[ w_{n+1} - \frac{1}{\lambda} \left( \frac{1}{a} - \frac{d}{\lambda^n} \right) \left( \frac{1}{b} - \frac{d}{\lambda^n} \right) w_{n-1} + \left( \frac{1}{ab\lambda} - 1 \right) w_n = 0. \] (5.10)

The linearization condition of q-P\( \text{V} \) was also given in [30], and shown that \( x_n \) can be expressed in terms of discrete analogue of confluent hypergeometric functions.

6 Conclusion

In this article, we have presented an algorithm which is similar to the algorithm introduced in [5] for continuous Painlevé equations, to obtain the Bäcklund transformations for discrete P\( \text{II-P} \text{V} \). The algorithm is simple and based on the investigation of discrete Riccati equation (1.5) for the solution of a given discrete Painlevé equation, with the coefficients depending linearly on the solution of another discrete equation of Painlevé type. The Miura transformation for d-P\( \text{II} \) and d-P\( \text{XXXIV} \), and the Bäcklund transformation for d-P\( \text{II} \) and d-P\( \text{IV} \) that we have presented, were previously known. The special-function solutions for the discrete Painlevé equations are extensively covered in the literature. But the transformations for q-P\( \text{II} \) and q-P\( \text{V} \) were not discussed in the literature before. Moreover, as an application of the algorithm, we have presented the special solutions which are discrete analogue of the classical special functions, for discrete P\( \text{II-P} \text{V} \) whenever the parameters satisfy certain conditions (the linearisability conditions).

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References


