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1.)

$$\bullet C_v = \frac{\partial x_g}{\partial T} u(v_g, T) + x_g \frac{\partial u_g}{\partial T} + \frac{\partial x_e}{\partial T} u_e + x_e \frac{\partial u_e}{\partial T}$$

$$x_g + x_e = 1$$

$$\frac{\partial x_g}{\partial T} = - \frac{\partial x_e}{\partial T}$$

$$C_v = x_g \frac{\partial u_g}{\partial T} + x_e \frac{\partial u_e}{\partial T} + (u_e - u_g) \frac{\partial x_e}{\partial T}$$

$$\bullet \left(\frac{\partial u_x}{\partial T} \right)_{\text{const}} = \frac{\partial u_x}{\partial T} + \left(\frac{\partial u_x}{\partial v_e} \right)_T \left(\frac{\partial v_e}{\partial T} \right)_v$$

• Clausius-Diagramm

$$\left(\frac{\partial P}{\partial T} \right)_{\text{const}} = \frac{\Delta T h_e - h_g}{T(v_e - v_g)} =$$

$$h_e = u_e + Pv_e$$

$$\left(\frac{\partial P}{\partial T} \right)_{\text{const}} = \frac{u_e - u_g + P(v_e - v_g)}{T(v_e - v_g)}$$

$$\Rightarrow (u_e - u_g) = \left[T \frac{\partial P}{\partial T} \right]_{\text{const}} - P(v_e - v_g)$$

$$\bullet \frac{\partial v_p}{\partial v_g} = 0 \quad v_p = x_e v_e + x_g v_g$$

$$\frac{\partial x_e}{\partial T} v_e + x_e \frac{\partial v_e}{\partial T} + \frac{\partial x_g}{\partial T} v_g + x_g \frac{\partial v_g}{\partial T} = 0$$

$$\frac{\partial x_e}{\partial T} (v_e - v_g) = - x_e \frac{\partial v_e}{\partial T} - x_g \frac{\partial v_g}{\partial T}$$

$$\frac{\partial x_e}{\partial T} = \frac{1}{(v_e - v_g)} \left[x_e \frac{\partial v_e}{\partial T} + x_g \frac{\partial v_g}{\partial T} \right]$$

(3)

$$\begin{aligned}
 C_v &= x_g \frac{\partial u_g}{\partial T} + x_e \frac{\partial u_e}{\partial T} + (u_e - u_g) \frac{\partial v_e}{\partial T} \\
 &= x_g \left[c_{vg} + \frac{\partial u_g}{\partial v_g} \frac{\partial v_g}{\partial T} \right] + x_e \left[c_{ve} + \frac{\partial u_e}{\partial v_e} \frac{\partial v_e}{\partial T} \right] \\
 &\quad + \frac{(u_e - u_g)}{(v_g - v_e)} \left[x_g \frac{\partial v_g}{\partial T} + x_e \frac{\partial v_e}{\partial T} \right] \\
 &= x_g \left[c_{vg} + \frac{\partial u_g}{\partial v_g} \frac{\partial v_g}{\partial T} \right] + x_e \left[c_{ve} + \frac{\partial u_e}{\partial v_e} \frac{\partial v_e}{\partial T} \right] \\
 &\quad - \left[T \left(\frac{\partial P}{\partial T} \right)_{\text{coex}} - \gamma \right] \left[x_g \frac{\partial v_g}{\partial T} + x_e \frac{\partial v_e}{\partial T} \right] \\
 &= x_g \left[c_{vg} + \left(T \left(\frac{\partial P_g}{\partial T} \right) - \gamma \right) \frac{\partial v_g}{\partial T} \right] \\
 &\quad + x_e \left[c_{ve} + \left(T \left(\frac{\partial P_e}{\partial T} \right) - \gamma \right) \frac{\partial v_e}{\partial T} \right] \\
 &\quad - \left[T \left(\frac{\partial P}{\partial T} \right)_{\text{coex}} - \gamma \right] \left[x_g \frac{\partial v_g}{\partial T} + x_e \frac{\partial v_e}{\partial T} \right] \\
 &= x_g c_{vg} + \gamma \left[x_e c_{ve} \right. \\
 &\quad \left. + x_g T \frac{\partial P_g}{\partial T} \frac{\partial v_g}{\partial T} + x_e T \frac{\partial P_e}{\partial T} \frac{\partial v_e}{\partial T} \right. \\
 &\quad \left. - T \left(\frac{\partial P}{\partial T} \right)_{\text{coex}} \left[x_g \frac{\partial v_g}{\partial T} + x_e \frac{\partial v_e}{\partial T} \right] \right] \\
 C_v &= x_g \left[c_{vg} - T \left(\frac{\partial P}{\partial v_g} \right)_T \left(\frac{\partial v_g}{\partial T} \right)^2_{\text{coex}} \right] \\
 &\quad + x_e \left[c_{ve} - T \left(\frac{\partial P}{\partial v_e} \right)_T \left(\frac{\partial v_e}{\partial T} \right)^2_{\text{coex}} \right]
 \end{aligned}$$

2. Ginzburg-Landau theory for the susceptibility

$$\Phi(T, \gamma, \delta) = \alpha_0(\tau, \gamma) + \alpha_2(T, \gamma)\gamma^2 + \alpha_4(T, \gamma)\gamma^4 - \delta\gamma$$

$$\frac{\partial \Phi}{\partial \gamma} = 2\alpha_2\gamma + 4\alpha_4\gamma^3 - \delta = 0$$

order parameter @ $\delta=0 \Rightarrow \gamma=0$
 $\gamma^2 = \sqrt{-\frac{\alpha_2}{2\alpha_4}}$

$$\alpha_2 = \alpha_0(T - T_c)$$

$$\gamma = \pm \sqrt{\frac{\alpha_0(T_c - T)}{2\alpha_4}}$$

susceptibility

$$\lim_{\delta \rightarrow 0} -\frac{\partial^2 \Phi}{\partial \delta^2} = \frac{\partial \gamma}{\partial \delta}$$

$$2\alpha_2 \frac{\partial \gamma}{\partial \delta} + 12\alpha_4\gamma^2 \frac{\partial \gamma}{\partial \delta} - 1 = 0$$

above critical point $\gamma=0$

$$\Rightarrow \chi = \frac{\partial \gamma}{\partial \delta} = \frac{1}{2\alpha_2} = \frac{1}{4\alpha_0(T - T_c)}$$

below critical point $\gamma = \pm \sqrt{\frac{\alpha_0(T_c - T)}{2\alpha_4}}$

$$\frac{\partial \gamma}{\partial \delta} = \frac{1}{2\alpha_2 + 12\alpha_4\gamma^2} = \frac{1}{2\alpha_2 + 12\frac{\alpha_0(T_c - T)}{2\alpha_4}} = -\frac{1}{4\alpha_2}$$

$$= -\frac{1}{4\alpha_0(T - T_c)} = \frac{1}{4\alpha_0(T_c - T)}$$

as $T \rightarrow T_c$ $\frac{\partial \gamma}{\partial \delta} \rightarrow \infty$

3.) van der Waals Equation of State

$$(P + \frac{a}{T v^2})(v - b) = RT$$

$$P = \frac{RT}{v-b} - \frac{a}{Tv^2}$$

$$\frac{\partial P}{\partial v} = -\frac{RT}{(v-b)^2} + \frac{2a}{Tv^3} = 0 \Rightarrow \frac{RT}{(v-b)^2} = \frac{2a}{Tv^3}$$

$$\frac{\partial^2 P}{\partial v^2} = \frac{2RT}{(v-b)^3} - \frac{6a}{Tv^4} = 0$$

$$= \frac{2}{(v-b)} \left(\frac{2a}{Tv^3} \right) - \frac{3}{v} \left(\frac{2a}{Tv^3} \right) = 0$$

$$2v - 3v + 3b = 0$$

$$\boxed{v_c = 3b}$$

$$\frac{RT_c^2}{4b^2} = \frac{2a}{27b}$$

$$T_c = \sqrt{\frac{8a}{27bR}}$$

$$P_c = \frac{2a(v_c-b)}{T_c v_c^2} - \frac{a v_c}{T_c v_c^3} = \frac{a}{T_c v_c^3} [v_c - 2b - \frac{1}{v_c}]$$

$$= \frac{a}{T_c v_c^3} [v_c - 2b]$$

$$= \frac{ab}{T_c 27b^2} = \frac{a}{27b^2} \sqrt{\frac{27bR}{8a}}$$

$$= \sqrt{\frac{aR}{216 \cdot b^3}}$$

To determine whether the law of corresponding states is satisfied \Rightarrow write equation of state in reduced variables and determine whether it depends on parameters a, b, R

$$\bar{P} = \frac{P}{P_c} = \left[\frac{R\bar{T}T_c}{V_c\bar{V}-b} - \frac{a}{T_c\bar{T}\bar{V}^2 V_c^2} \right] \frac{1}{P_c}$$

$$\bar{P} = \left[\frac{R\bar{T}T_c}{V_c\bar{V}-b} - \frac{a}{T_c\bar{T}\bar{V}^2 V_c^2} \right] \frac{1}{P_c}$$

$$= \left[\frac{R\bar{T}T_c}{3b\bar{V}-b} - \frac{a}{T_c\bar{T}\bar{V}^2 9b^2} \right] \frac{1}{P_c}$$

$$= \left[\frac{\bar{T}}{3\bar{V}-1} \frac{(RT_c)}{b} - \frac{12a}{\bar{T}\bar{V}^2} \left(\frac{a}{T_c b^2} \right) \right] \frac{1}{P_c}$$

$$= \frac{\bar{T}}{3\bar{V}-1} \left(\frac{RT_c}{b P_c} \right) - \frac{1}{\bar{T}\bar{V}^2} \left(\frac{a}{P_c T_c 9b^2} \right)$$

$$\frac{RT_c}{b P_c} = \frac{R}{8} \left(\frac{8a}{27\alpha R} \right)^{1/2} \left(\frac{216\alpha^3}{\alpha R} \right)^{1/2} = 8$$

$$\left(\frac{a}{P_c T_c 9b^2} \right) = \frac{\alpha}{9b^2} \left(\frac{216\alpha^3}{\alpha R} \right)^{1/2} \left(\frac{172\alpha R}{8\alpha} \right)^{1/2} = \frac{27}{a} = 3$$

$$\boxed{\bar{P} = \frac{8\bar{T}}{3\bar{V}-1} - \frac{3}{\bar{T}\bar{V}^2}}$$

\Rightarrow law of corresponding states is satisfied

4.)

$$\bullet G = U - TS + PV = \mu_A N_A + \mu_B N_B$$

• differential:

$$dG = dU - TdS - SdT + PdV + VdP$$

~~but~~

$$\text{since } U = TS - PV \quad \forall H, N_i$$

$$dU = TdS + \cancel{SdT} - PdV + \mu_A dN_A + \mu_B dN_B$$

(fundamental equation of thermodynamics)

$$dG = - SdT + VdP + \mu_A dN_A + \mu_B dN_B$$

• Gibbs-Duhem equation:

$$SdT - VdP + \sum N_k d\mu_k = 0$$

$$\text{divide by } N = N_A + N_B$$

$$SdT - \alpha dP + \sum x_k d\mu_k = 0$$

• Clausius-Clapeyron

dG - at two phases (in molar units)

$$dG^I = - S^I dT + V^I dP + (\mu_A^I - \mu_B^I) dN_I$$

$$dG^{II} = - S^{II} dT + V^{II} dP + (\mu_A^{II} - \mu_B^{II}) dN_{II}$$

$$\left(\frac{dP}{dT}\right)_{\text{const}} = \frac{\Delta S}{\Delta V} - \frac{(\mu_A - \mu_B)}{\Delta V} \frac{d\ln x}{dT}$$