

Problem Set 12: Solutions

①

1.) (a) ρ two regions $r < R$ (R radius of sphere)
 $r > R$



Gauss' law $\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_0}$

$r < R$ $E 4\pi r^2 = \frac{1}{\epsilon_0} \frac{4\pi r^3 \rho}{3}$ \Rightarrow

$E = \frac{\rho r}{3\epsilon_0}$

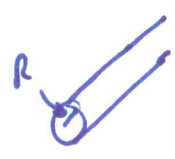
$r > R$ $E 4\pi r^2 = \frac{1}{\epsilon_0} \frac{4\pi R^3 \rho}{3}$

$E = \frac{\rho R^3}{3\epsilon_0 r^2}$



(b) cylinder: radius R

$r < R$
 $r > R$



Gaussian surface: \rightarrow



associate length L with cylinder

for $r < R$ $\oint E \cdot d\vec{A} = E 2\pi r L$

$Q_{enclosed} = \rho \pi r^2 L$

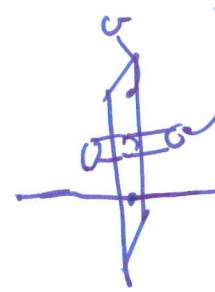
$\Rightarrow E 2\pi r L = \frac{\rho \pi r^2 L}{\epsilon_0} \Rightarrow E = \frac{\rho r}{2\epsilon_0}$

for $r > R$

$E 2\pi r L = \rho \pi R^2 L$

$E = \frac{\rho R^2}{2r}$

(c)

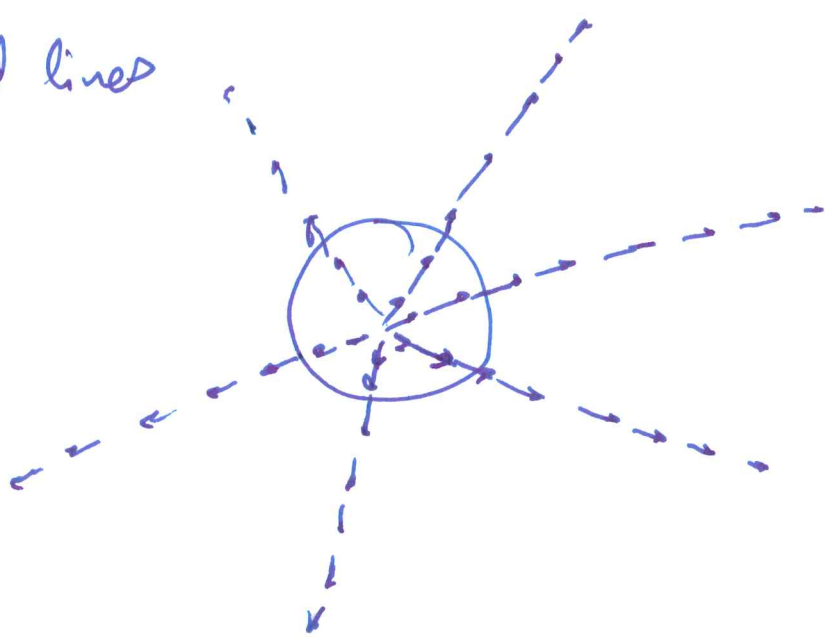


Gaussian surface:
 (cylinder
 w/ radius r ,
 length L)

$\oint \vec{E} \cdot d\vec{A}$
 $= 2E\pi r^2 = \frac{\sigma \pi r^2}{\epsilon_0}$

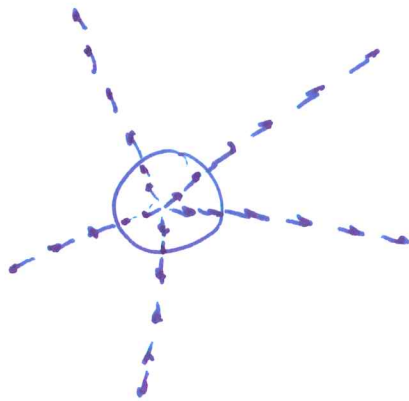
$\Rightarrow E = \frac{\sigma}{2\epsilon_0}$

electric field lines
sphere

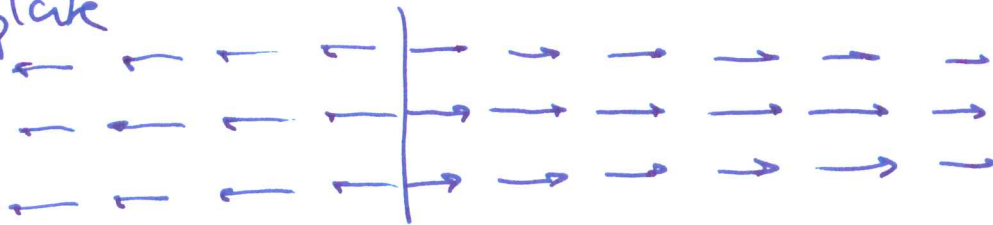


(2)

Cylinder



plate



2.) 1.(a) use reference point $r = \infty$

$$r > R \quad V(r) = - \int_{\infty}^r E(r') dr' = - \int_{\infty}^r \frac{\rho R^3}{3\epsilon_0 r'^2} dr'$$

$$= - \frac{\rho R^3}{3\epsilon_0} \int_{\infty}^r \frac{dr'}{r'^2} = + \frac{\rho R^3}{3\epsilon_0 r}$$

$$r < R \quad V(r) = - \int_R^r E(r') dr' + \frac{\rho R^2}{3\epsilon_0}$$

$$= - \int_R^r \frac{\rho r'}{3\epsilon_0} dr' + \frac{\rho R^2}{3\epsilon_0} = \frac{\rho}{3\epsilon_0} \frac{r'^2}{2} \Big|_R^r + \frac{\rho R^2}{3\epsilon_0}$$

$$= \frac{\rho}{6\epsilon_0} (r^2 - R^2) + \frac{\rho R^2}{3\epsilon_0} = \frac{\rho}{6\epsilon_0} (r^2 + R^2)$$

1.) b.) choose reference potential to be at radius of cylinder ($r = R$) (3)

for $r > R$
$$V(r) = - \int_R^r E(r') dr'$$

$$= - \frac{\lambda R^2}{2\epsilon_0} \int_R^r \frac{dr'}{r'}$$

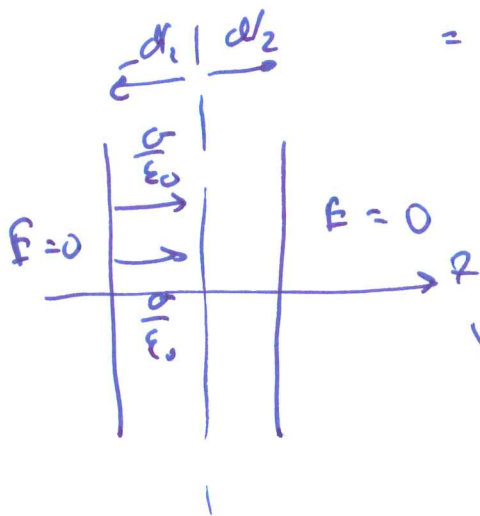
$$= - \frac{\lambda R^2}{2\epsilon_0} \ln r' \Big|_R^r$$

$$= - \frac{\lambda R^2}{2\epsilon_0} \ln r/R = \frac{\lambda R^2}{2\epsilon_0} \ln R/r$$

for $r < R$
$$V(r) = - \int_R^r E(r') dr'$$

$$= - \frac{\lambda}{2\epsilon_0} \int_R^r r' dr' = - \frac{\lambda}{2\epsilon_0} \frac{r'^2}{2} \Big|_R^r$$

$$= - \frac{\lambda}{4\epsilon_0} (r^2 - R^2) = \frac{\lambda}{4\epsilon_0} (R^2 - r^2)$$



$V(-d/2) = 0$ (reference point)

$$V(x) = - \int_{-d/2}^x E \cdot dx'$$
 (for $-d/2 < x < d/2$)

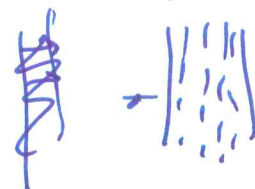
$$= - \frac{\sigma}{\epsilon_0} x' \Big|_{-d/2}^x$$

$$V(x) = - \frac{\sigma}{\epsilon_0} (x + d/2)$$

equipotential surfaces

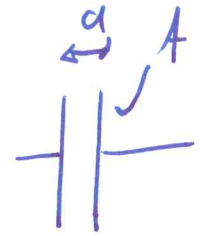


parallel plate capacitor: planes



3.)

(4)



Slab (conducting)

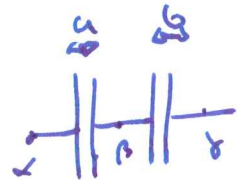


$$V = \frac{Q}{C}$$

$$E_d = \frac{\sigma A}{C} = \frac{\sigma d}{\epsilon_0} \Rightarrow C = \frac{\epsilon_0 A}{d}$$

$C = ?$

new arrangement is like two capacitors in series



$$a + b = d - w$$

$$C_1 = \frac{\epsilon_0 A}{a}$$

$$C_2 = \frac{\epsilon_0 A}{b}$$

capacitors in series:

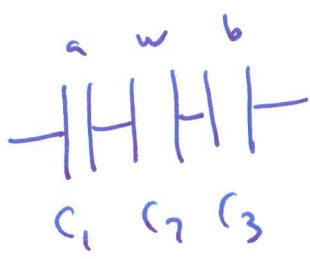
$$V_{d\gamma} = V_{d\beta} + V_{\beta\gamma}$$

$$\frac{Q}{C_{eq}} = \frac{Q}{C_1} + \frac{Q}{C_2} \Rightarrow \frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2}$$



$$\frac{1}{C_{eq}} = \frac{a}{\epsilon_0 A} + \frac{b}{\epsilon_0 A} = \frac{a+b}{\epsilon_0 A} = \frac{d-w}{\epsilon_0 A}$$

- for slab with dielectric: three capacitors in series



$$a + w + b = d$$

$$C_1 = \frac{\epsilon_0 A}{a}$$

$$C_2 = \frac{k \epsilon_0 A}{w}$$

$$C_3 = \frac{\epsilon_0 A}{b}$$

$$\frac{1}{C_{eq}} = \frac{a + w/k + b}{\epsilon_0 A} \Rightarrow$$

$$C_{eq} = \frac{\epsilon_0 A}{a + \frac{w}{k} + b}$$



$E = \rho J$

$R = \frac{\rho L}{A}$

$EL = \rho J L$

$V = \rho J L = \frac{\rho I L}{A} \Rightarrow I = \frac{VA}{\rho L}$

power dissipated

$P = I^2 R = \frac{V^2 A^2}{\rho^2 L^2} \frac{\rho L}{A} = \frac{V^2 A \rho}{\rho^2 L} = \frac{V^2 A}{\rho L}$

$P = \frac{V^2 A}{\rho L}$

$I = \frac{VA}{\rho L}$

\sqrt{A}

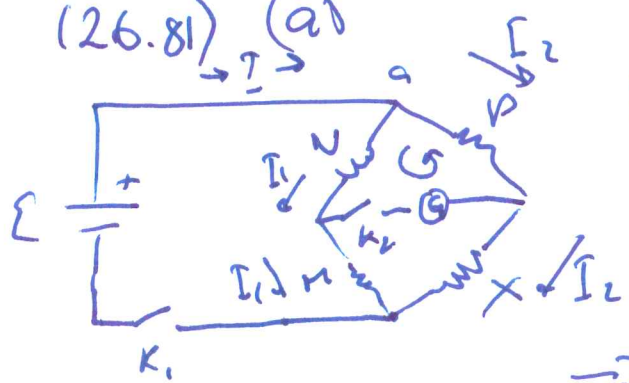
~~$P = 30P$~~

$P = \frac{E^2 LA}{\rho}$

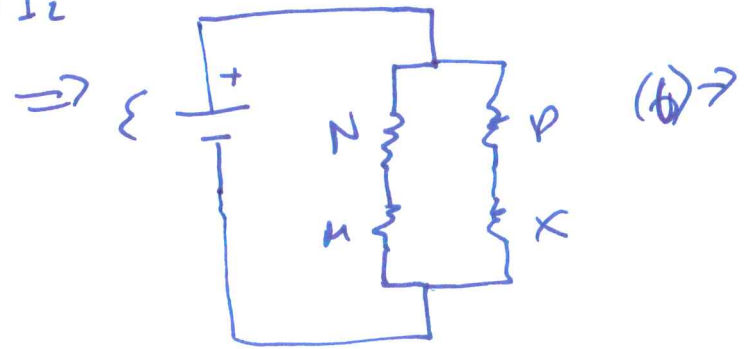
$I = \frac{EA}{\rho}$

$A \rightarrow 4A, L \rightarrow 17.5L \Rightarrow P \rightarrow 30P, I \rightarrow 4I$

5.) (26.81) (a)



(a) when balanced (current in G is zero)



equivalent resistance of bridge

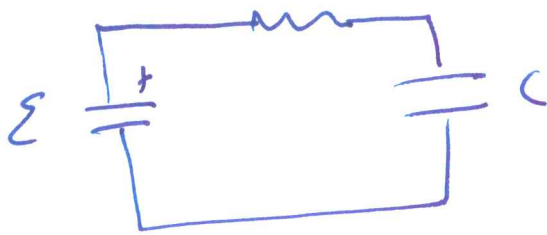
$\frac{1}{R_{eq}} = \frac{1}{M+N} + \frac{1}{P+X}$

we also have: loops $\Rightarrow NI_1 = PI_2$ ($MI_1 = XI_2 \Rightarrow X = \frac{MN}{P}$)

(b) 1897-7

(6)

(b) (26.90) R



$$\mathcal{E} - IR - \frac{Q}{C} = 0$$

$$\mathcal{E} - \frac{dQ}{dt}R - \frac{Q}{C} = 0$$

$$\mathcal{E}C - \frac{dQ}{dt}(RC) - Q = 0$$

$$-\frac{dQ}{dt}(RC) = Q - \mathcal{E}C$$

$$-\frac{dt}{RC} = \frac{dQ}{Q - \mathcal{E}C}$$

$$Q(0) = 0$$

$$-\frac{t}{RC} = \ln \left(\frac{Q(t) - \mathcal{E}C}{Q(0) - \mathcal{E}C} \right)$$

$$-\mathcal{E}C e^{-t/RC} = Q(t) - \mathcal{E}C$$

$$Q(t) = \mathcal{E}C (1 - e^{-t/RC})$$

$$(a) Q(\infty) = 1000V \times 10.0 \text{ pF} = 1000V \times 10.0 \times 10^{-12} \text{ F} \\ = 10.0 \times 10^{-9} \text{ C} = 10.0 \text{ nC}$$

$$(b) Q(0) = \mathcal{E}C \quad (\mathcal{E} = 1000V \\ C = 10.0 \text{ pF} \rightarrow \text{original capacitance})$$

$$Q(t) = \mathcal{E}C' (1 - e^{-t/RC'})$$

$$\text{in general: } Q(t) = (Q(0) - \mathcal{E}C') e^{-t/RC'} + \mathcal{E}C' \\ = Q(0) + \mathcal{E}C'(1 - e^{-t/RC'})$$

where C' is the new capacitance

$$Q(0) = \mathcal{E}C$$

$$\Downarrow \\ Q(t) = \mathcal{E}C + \mathcal{E}C'(1 - e^{-t/RC'}) \Rightarrow I(t) = \frac{\mathcal{E}}{R} e^{-t/RC'}$$

$$I(t) = \frac{\epsilon}{R} e^{-t/RC}$$

①

if R too large $\rightarrow I(t)$ too small to be detected

if R too small $\rightarrow I(t)$ decays too fast to zero and will not be detected

6.) mass m charge q potential difference V

$$\text{energy} = qV$$

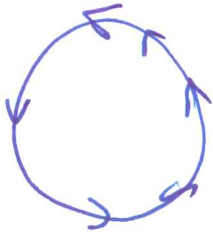
$$\frac{mv^2}{2} = qV \Rightarrow \text{velocity } \sqrt{\frac{2qV}{m}} = v$$

radius of cyclotron motion

$$qvB = \frac{mv^2}{r} = r = \frac{mv}{qB} = \frac{m}{qB} \sqrt{\frac{2qV}{m}}$$

$$= \sqrt{\frac{2mV}{qB^2}}$$

7.)

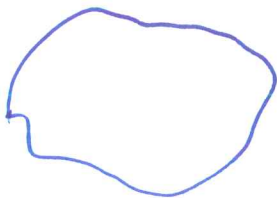


$$\vec{F} = I \oint d\vec{l} \times \vec{B}$$

$$= I \oint dL B \sin \theta$$

$$= IB \oint dL \sin \theta$$

in general (loop does not need to be circular)



$$F_x = I \oint (dL_y B_z - dL_z B_y)$$

$$= IB_z \oint dL_y - IB_y \oint dL_z$$

$$\oint dL_z = 0 \quad \text{loop integral}$$

which goes from some point back to the same point

$$\Rightarrow F_x = 0 \quad F_z = 0 \quad (\text{same proof})$$

7. (cont): for inhomogeneous magnetic field
result does not hold

(8)

8.) $\vec{j}(r) = j_0 \left(1 - \left(\frac{r}{r_0}\right)^3\right)$

total current:
$$I = \int \vec{j} \cdot d\vec{A}$$

$$= 2\pi j_0 \int_0^{r_0} r dr \left(1 - \frac{r^3}{r_0^3}\right)$$

$$= 2\pi j_0 \left(\frac{r^2}{2} - \frac{r^5}{5r_0^3}\right)$$

$$= 2\pi j_0 r_0^2 \left(\frac{3}{10}\right) = \frac{3\pi}{5} j_0 r_0^2$$

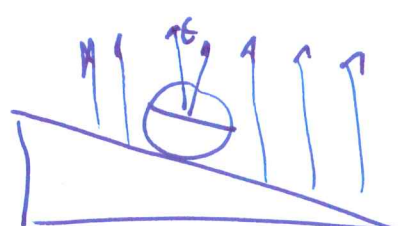
(b) magnetic field (Ampère's law)

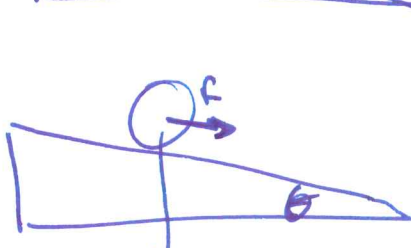
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

$$B 2\pi r = 2\pi j_0 \int_0^r r' dr' \left(1 - \frac{r'^3}{r_0^3}\right)$$

$$= 2\pi j_0 \left(\frac{r^2}{2} - \frac{r^5}{5r_0^3}\right)$$

$$B = j_0 \left(\frac{r}{2} - \frac{r^4}{5r_0^3}\right)$$

9.)  mag. torque $\vec{\tau}_D = \vec{\mu} \times \vec{B} \Rightarrow I A B \sin \theta$
grav. torque $= I L 2R B \sin \theta$

 $f = mg \sin \theta$

$a = g \sin \theta$ $r \alpha = g \sin \theta$
 $\alpha = \frac{g \sin \theta}{R}$ $\tau_D = I_r \alpha =$

$I_r =$

$$I_r = 2\pi \int_0^R \rho v^2 r dr L$$

$$= 2\pi L \rho \int_0^R r^3 dr = \frac{2\pi L \rho R^4}{4}$$

(9)

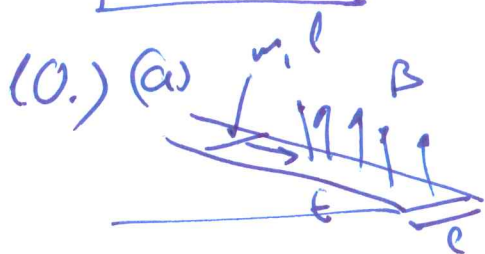
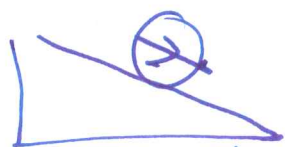
total mass $2\pi \rho \int_0^R r dr L = \frac{2\pi \rho L R^2}{2}$

$$I_r = \frac{MR^2}{2}$$

$$\tau_g = \tau_B \quad \frac{mR^2}{2} \frac{g \sin \theta}{R} = I L 2R B \sin \theta$$

$$B \sin \theta \quad I = \frac{mg}{4LB}$$

direction of current:



gravitational force

$$f_g = mg \sin \theta$$

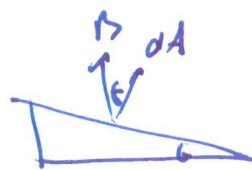
should be balanced by magnetic force

$$f_B = I l B \cos \theta$$

$$I l B \cos \theta = mg \sin \theta$$

$$I = \frac{mg \tan \theta}{l B}$$

$$\mathcal{E} = - \frac{d\Phi_B}{dt} = I R$$



$$\mathcal{E}_B = \int \mathbf{B} \cdot d\mathbf{A} = B l v \cos \theta = I R$$

$$I = \frac{B l v \cos \theta}{R} = \frac{mg \sin \theta}{l B \cos \theta} \Rightarrow v = \frac{mg R \sin \theta}{B^2 l^2 \cos^2 \theta}$$

(b) dissipated power

(10)

$$P_B = I^2 R = \frac{B^2 l^2 v^2 \cos^2 \theta}{R^2} R = B^2 l^2 v^2 \cos^2 \theta$$
$$= m^2 g^2$$

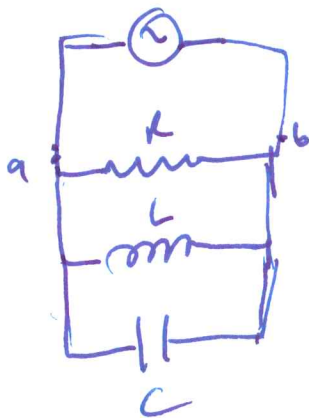
~~mg~~ =

potential energy change / unit time

$$P_g = mg v \sin \theta = \frac{mg \cdot mg R \sin^2 \theta}{B^2 l^2 \cos^2 \theta}$$

$$= \frac{m^2 g^2 \sin^2 \theta}{B^2 l^2 \cos^2 \theta} R = I^2 R \quad \checkmark$$

11. (31.56)



$$v = V \cos \omega t$$

(a) they are all equal since one can take path from a to b
across resistor $\rightarrow v_{ab}$
across inductor $\rightarrow v_{ab}$
across capacitor $\rightarrow v_{ab}$
all since same potential difference

$$v = i_R R$$

$$i = i_R + i_L + i_C$$

$$V \cos \omega t = I_R R \cos \omega t$$

$$V = I_R R$$

inductor:

$$V \cos \omega t = v = L \frac{di_L}{dt}$$

$$V \cos \omega t = L \frac{di_L}{dt}$$

$$\frac{V \sin \omega t}{\omega} = L i_L(t) \Rightarrow i_L = \frac{V}{\omega L} \sin \omega t$$

$$i_L = I_L \sin \omega t$$

$$\omega L \bar{I}_L = V \Rightarrow V = X_L \bar{I}_L \Rightarrow v = V \cos \omega t$$

$$i_R = \bar{I}_R \cos \omega t$$

$$i_C = \bar{I}_C \sin \omega t = \bar{I}_C \cos(\omega t - \frac{\pi}{2})$$

(19)

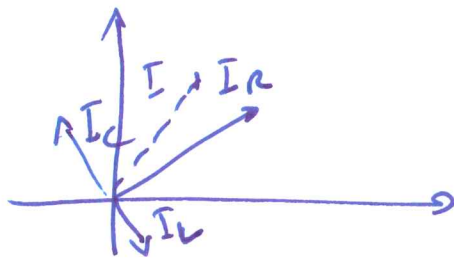
capacitor:

$$V \cos \omega t = \frac{q}{C}$$

$$-V \omega \sin \omega t = \frac{\dot{q}}{C} \Rightarrow \dot{q} = -\omega C V \sin \omega t = I_C \cos(\omega t + \frac{\pi}{2})$$

$$= -\frac{V}{X_C} \sin(\omega t + \frac{\pi}{2})$$

current phasor diagram:



$$I = \sqrt{(I_C - I_R)^2 + I_L^2}$$

$$I = \sqrt{V^2 \left(\frac{1}{X_C} - \frac{1}{X_L} \right)^2 + \frac{1}{R^2}}$$

$$I = V \sqrt{\left(\frac{1}{X_C} - \frac{1}{X_L} \right)^2 + \frac{1}{R^2}}$$

$$I = V \sqrt{\left(\omega C - \frac{1}{\omega L} \right)^2 + \frac{1}{R^2}}$$

$$Z = \frac{1}{\sqrt{\left(\omega C - \frac{1}{\omega L} \right)^2 + \frac{1}{R^2}}}$$

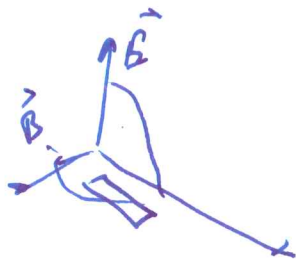
(12)

$$\vec{E} = E_{max} \hat{j} \cos(kx - \omega t)$$

$$\vec{B} = B_{max} \hat{i} \cos(kx - \omega t + \phi)$$

use Ampère's or Faraday's law

Ampère:



$$\oint \vec{B} \cdot d\vec{l} = \epsilon_0 \mu_0 \frac{\partial \Phi_E}{\partial t}$$

$$[B(x + \Delta x, t) - B(x, t)] a = -\epsilon_0 \mu_0 \frac{\partial E(x, t)}{\partial t} a \Delta x$$

$$\frac{\partial B(x, t)}{\partial x} = -\epsilon_0 \mu_0 \frac{\partial E(x, t)}{\partial t}$$

$$-k B_{max} \cos(kx - \omega t + \phi) = -\epsilon_0 \mu_0 \omega E_{max} \cos(kx - \omega t)$$

satisfied if $E_{max} = c B_{max}$ $c = \frac{1}{\sqrt{\epsilon_0 \mu_0}} = \frac{c}{k}$

$$\phi = 0$$